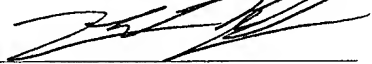


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Method and Apparatus for Local Image Quantification Verification

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BACKGROUND OF THE INVENTION

1. Field of the Invention

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This invention relates generally to the field of computer software and computer program testing. More specifically, it relates to verification of graphics images produced by a computer graphics program.

2. Description of the Related Art

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Early graphics systems were limited to two-dimensional (2D) graphics and acted as simple translators or interfaces to a display device. Modern graphics systems, however, support three-dimensional (3D) graphics with textures and many special effects such as anti-aliasing, texture mapping, advanced shading, fogging, alpha-blending, and specular highlighting. Modern computer displays have many more pixels, greater color depth, and are able to display more complex images with higher refresh rates than earlier models. Consequently, modern graphics systems incorporate graphics processors with a great deal of complexity, and the color value of one pixel can be the accumulated result of many calculations involving several models and mathematical approximations.

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Software testing has experienced a similar transformation. As the complexity of the calculations and the layering of effects increased, the amount of time required to test and evaluate graphics software also increased and has become a significant bottleneck in the software development timeline. The evaluation of new graphics software may involve thousands of tests and require the judgment and experience of a senior test engineer to sort through the many possible reasons for a test failure. There may be more than one bug in a software program, and the cumulative result may cause a pixel in an output image to be different from a pixel in a reference image. In addition, there are many combinations and versions of hardware and software that may be used to generate a test image. It is not practical to generate a set of reference images for each of these combinations.

One method of testing graphics software is known as sample point testing. In this method the expected values of each pixel in a reference image generated by a specific hardware/software configuration is hardcoded in a test program. Each pixel of a test image is evaluated versus the hardcoded data in the test program. A difference image is formed by subtracting the value of a test image pixel from the value of the corresponding reference image pixel. Corresponding pixels are pixels located at the same x and y coordinates in both the test image and the reference image. Consequently, the test program user is easily overwhelmed, since the test evaluation output (the difference image) is as complex as the test image. In addition, the test program must be updated for any equipment or software modifications and each reference image requires a new test program. Maintaining and updating the test programs is both time consuming and error prone.

Other types of test programs are described in U.S. Patent No. 6,226,406, issued on May 1, 2001, entitled "Method and Apparatus for Hybrid Sampling Image Verification" by Teh-Ming Hsieh.

A more efficient, faster, automated method of testing images generated on various combinations of computer graphics software and hardware using a limited set of reference images is needed. It would be desirable for the method to accept insignificant rendering differences, and to provide a simple "pass or fail" decision or a simple quantifiable measurement of the image comparison.

SUMMARY

The problems outlined above may, in some embodiments, be solved in part by limiting the number of reference images used for comparison in evaluating the accuracy of test images, by using a test program that renders a “pass or fail” decision for a test image, and/or by relaxing the requirement that test image color values exactly match the color values in a reference image. Instead, test image color values that are within a user specified percentage of the average color value of a corresponding array of pixels in the reference image may be acceptable. In addition, the specified percentage can be tailored to fit the accuracy required for a given portion (or region) of the test image, or the rendering of a given object. In other embodiments, a test image may be deemed acceptable if there is an acceptable shift in corresponding pixel locations. This standard accepts a rendering process that shifts, enlarges, or shrinks an object within user specified limits. In still other embodiments, a user may define regions of interest with specific maximum differences for each region. This allows a user to specify the accuracy of certain regions of the test image as more critical than others and to focus a region on a particular object or group of objects with a narrow range of color values.

In some embodiments, the reference image may be an image generated by a given computer graphics program executing on a given computer graphics system. In another embodiment, the reference image may be generated by calculating the color values of each pixel, i.e. equations describing a given set of transformations and lighting processes may be applied to a given set of objects composing the image to determine the color value of each pixel. In still another embodiment, the reference image may be created by a combination of these two methods.

One embodiment of a test program identified herein as global image quantification verification may incorporate user-defined regions of interest with specific error tolerances for each region, and may generate one or more measurements of error or image difference for each region of the test image. Each region of the test image may be divided into sub-regions and an average color value may be calculated for each test image sub-region and the corresponding sub-region in the reference image. The absolute differences between the averages for the

corresponding sub-regions in the test and reference images are calculated. A test image region may be unacceptably different from a reference image if a normalized sum of the absolute differences exceeds a user specified maximum difference. This method effectively blurs both the test image and the reference image.

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Another embodiment of a test program for determining the accuracy of digital test images is identified herein as regional image quantification verification. This test program may incorporate user-defined regions of interest with specific error tolerances for each region and an image comparison that accepts minor color value and spatial shifts. Each region of the test image and reference image may be divided into sub-regions. The average color value for each sub-region of the test image may be compared to the average color value of the corresponding reference image sub-region and also to nearby reference image sub-regions. A test image region may be unacceptably different from a reference image if for any sub-region of the test image region, a reference image sub-region can not be found that has an average color value difference and spatial shift less than user specified maximums.

Still another embodiment of a test program for determining the accuracy of digital test images is identified herein as local image quantification verification. This test program may incorporate user-defined regions of interest with specific error tolerances for each region and may incorporate an image comparison that allows color value differences. Each pixel of a specified region of a test image may be compared to the corresponding pixel of a reference image, or to an average color value for a corresponding array of pixels in a reference image. If the color value of a test image pixel is within a specified difference from the color value of the corresponding reference image pixel, the test image pixel passes. If not, a larger array of pixels in the reference image is selected and the test is repeated. This sequence ends whenever the test image pixel passes, or when a specified maximum size array of reference image pixels is exceeded. A test image region may be unacceptably different from a reference image if for any pixel of the test image region, there is no corresponding reference image pixel or pixel array that has an array size or absolute color value difference less than or equal to user specified maximums. This method effectively blurs the reference image in progressive stages.

Yet still another embodiment of a test program for determining the accuracy of digital test images is identified herein as adaptive local image quantification verification. This test program may incorporate user-defined regions of interest with specific error tolerances for each region and may incorporate an image comparison that allows color value differences and spatial shifts. In addition to the process described for local image quantification verification, each pixel of a specified region of the test image may also be compared to the average color value of a corresponding, but possibly offset array of pixels in a reference image. A test image region may be unacceptably different from a reference image if for any pixel of the test image region, a reference image array can not be found that has an array size, absolute color value difference, and spatial shift less than user specified maximums.

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BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing, as well as other objects, features, and advantages of this invention may be more completely understood by reference to the following detailed description when read
5 together with the accompanying drawings in which:

Figure 1 depicts an example of a computer system capable of image quantification verification;

10 Figure 2 is a simplified block diagram illustrating one embodiment of a computer system capable of image quantification verification;

Figure 3 is a flowchart of one embodiment of a method used to perform local image quantification verification;

Figure 4 is a flowchart of one embodiment of a method used to perform adaptive local image quantification verification;

Figure 5 is a flowchart of one embodiment of a method used to perform an offset array test as part of the method for adaptive local image quantification verification;

Figure 6 is a flowchart of one embodiment of a method used to perform global image quantification verification; and

25 Figure 7 is a flowchart of one embodiment of a method used to perform regional image quantification verification.

While the invention is susceptible to various modifications and alternative forms, specific embodiments thereof are shown by way of example in the drawings and will herein be described
30 in detail. It should be understood, however, that the drawings and detailed description thereto are not intended to limit the invention to the particular form disclosed, but on the contrary, the

intention is to cover all modifications, equivalents, and alternatives falling within the spirit and scope of the present invention as defined by the appended claims. Note, the headings are for organizational purposes only and are not meant to be used to limit or interpret the description or claims. Furthermore, note that the word “may” is used throughout this application in a permissive sense (i.e., having the potential to, being able to), not a mandatory sense (i.e., must).” The term “include”, and derivations thereof, mean “including, but not limited to.” The term “connected” means “directly or indirectly connected”, and the term “coupled” means “directly or indirectly connected”.

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DETAILED DESCRIPTION OF SEVERAL EMBODIMENTS

Figure 1 - Computer System

Figure 1 illustrates one embodiment of a type of computer system 80 used to generate a test image and may also be configured to perform image quantification verification tests. The computer system 80 may be configured to include various devices, including a personal computer, a network PC, an Internet appliance, a television (including HDTV systems and interactive television systems), a personal digital assistant (PDAs), a virtual reality system, and other devices which display 2D and or 3D graphics, among others.

As shown, the computer system 80 includes a system unit 82 and a video monitor or display device 84 coupled to the system unit 82. The display device 84 may be any of various types of display monitors or devices (e.g., a CRT, LCD, or gas-plasma display). Various input devices may be connected to the computer system, including a keyboard 86 and/or a mouse 88, or other input device (e.g., a trackball, digitizer, tablet, six-degree of freedom input device, head tracker, eye tracker, data glove, or body sensors). Application software may be executed by the computer system 80 to display graphical objects on display device 84 or to perform image quantification verification tests.

Figure 2 - Computer System Block Diagram

Figure 2 presents a simplified block diagram illustrating the computer system of Figure 1. Elements of the computer system that are not necessary for an understanding of the present invention are not shown for convenience. As shown, the computer system 80 includes a host central processing unit (CPU) 102 coupled to a high-speed memory bus or system bus 104 also referred to as the host bus 104. A main memory 106 may also be coupled to high-speed bus 104.

Host CPU 102 may include one or more processors of varying types, e.g., microprocessors, multi-processors and CPUs. The main memory 106 may include any combination of different types of memory subsystems, including random access memories, (e.g., static random access memories or "SRAMs," synchronous dynamic random access memories or

“SDRAMs,” and Rambus dynamic random access memories or “RDRAM,” among others) and mass storage devices. The system bus or host bus 104 may include one or more communication or host computer buses (for communication between host processors, CPUs, and memory subsystems) as well as specialized subsystem buses.

5 A graphics system 112 is coupled to the high-speed memory bus 104. The graphics system 112 may be coupled to the bus 104 by, for example, a crossbar switch or other bus connectivity logic. It is assumed that various other peripheral devices, or other buses, may be connected to the high-speed memory bus 104. It is noted that the graphics system may be coupled to one or more of the buses in computer system 80 and/or may be coupled to various types of buses. In addition, the graphics system may be coupled to a communication port and thereby directly receive graphics data from an external source, e.g., the Internet or a network. As shown in the figure, one or more display devices 84 may be connected to the graphics system 112 included in the computer system 80.

Host CPU 102 may transfer information to and from the graphics system 112 according to a programmed input/output (I/O) protocol over host bus 104. Alternately, graphics system 112 may access the main memory 106 according to a direct memory access (DMA) protocol or through intelligent bus mastering.

A graphics application program conforming to an application programming interface (API) such as OpenGL® or Java 3D™ may execute on host CPU 102 and generate commands and data that define a geometric primitive (graphics data) such as a polygon for output on display device 84. Host CPU 102 may transfer this graphics data to the main memory subsystem 106. Thereafter, the host CPU 102 may operate to transfer the graphics data to the graphics system 112 over the host bus 104. In another embodiment, the graphics system 112 may read in geometry data arrays over the host bus 104 using DMA access cycles. In yet another embodiment, the graphics system 112 may be coupled to the main memory 106 through a direct port, such as the Advanced Graphics Port (AGP) promulgated by Intel Corporation.

The graphics system may receive graphics data from any of various sources, including the host CPU 102 and/or the main memory 106, other memory, or from an external source such

as a network, e.g., the Internet, or from a broadcast medium, e.g., television, or from other sources.

Note while graphics system 112 is depicted as part of computer system 80, graphics system 112 may also be configured as a stand-alone device (e.g., with its own built-in display).

5 Graphics system 112 may also be configured as a single chip device or as part of a system-on-a-chip or a multi-chip module. Additionally, in some embodiments, certain elements of the illustrated graphics system 112 may be implemented in software.

Figure 3 – Local Image Quantification Verification

10 Local image quantification verification is a self-adaptive image comparison test program. In one embodiment, the user defines one or more regions of the test image to be individually compared to a reference image and restricts the comparison to those pixels that are within the specified region or regions. A region of the test image may also be specified as the combination of two or more disjoint regions. This allows the test comparison to focus on one object, a small group of objects, a set of common objects, or a region with some common characteristic, such as a sky color. By repeating the comparison for several different portions of the test image, a set of Pass/Fail results can be independently determined for different objects or regions.

20 The value of a test image pixel $T(x,y)$ is first compared to the value of the corresponding reference image pixel $R(x,y)$. Corresponding pixels are pixels located at the same x and y coordinates in image space, one each from the test image and the reference image. If the difference between the corresponding pixels is greater than a user specified limit (or maximum difference), the average value of an array of reference image pixels centered on the pixel $R(x,y)$ is compared to the value of the test image pixel. In other embodiments, the array of reference image pixels may not be centered on the pixel $R(x,y)$, but instead be offset and located near the pixel $R(x,y)$ and may or may not include the pixel $R(x,y)$. These methods effectively blur the
25 reference image to identify an acceptable match.

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Figure 3 illustrates one set of embodiments of the local image quantification verification test program. The test program is first initialized 300 by storing the reference image and test image or by specifying where they may be accessed. Storing an image includes one or more steps of reading an image from a storage medium, receiving an image from the Internet or from an intranet, transferring a reference image from another computer system, or calculating a value for each pixel of a reference image from equations describing each graphics operation used to create the test image. In one embodiment of the test program, a batch of images may be stored, with one or more test images and one or more reference images. The user may specify which test image and reference image comparisons to perform. A limit (also referred to as a maximum percent difference, max %, or maximum difference) is specified for the difference between the value of the test image pixel and the corresponding value of a reference image pixel (or average value of a reference image pixel array). A limit or maximum size is also specified for a reference image pixel array. The portion (region or regions) of the test image to be evaluated is specified and the first test image pixel to be compared is selected.

The reference image array size may be controlled by an index parameter $k = 0, 1, 2, 3, \dots, N$ and initially may be set equal to zero 310. The selected array of reference image pixels is $(2k+1)$ by $(2k+1)$. This selects one of the set of pixel arrays $\{1 \times 1, 3 \times 3, 5 \times 5, 7 \times 7, \dots, \text{maximum size array}\}$ 315. In some embodiments, the reference image array may be a rectangular array of pixels, a circular array of pixels, or a specified grouping of pixels. The reference image pixel array is selected so that it is centered on the pixel that corresponds to the position of the test image pixel 320. The average value of the reference image array is calculated 325 and compared to the value of the test image pixel 330. If the absolute difference is greater than the specified limit, and the array size is less than the maximum array 335, then k is increased by one 345 and the comparison is repeated for $k = k+1$ 315 through 330. If the absolute difference is greater than the specified limit, and the array size is equal to the maximum array 335 the test is terminated and the comparison is labeled a failure 355. If the absolute difference is less than the specified limit, the test pixel passes and the test program checks for untested pixels 340. If there is an untested pixel, a comparison is initiated 350. The array index parameter is re-set to zero 310 and the comparison process is repeated 315 through 330. If all pixels in the specified region

of the test image have successfully passed the comparison test, the comparison is labeled a pass 360.

In some embodiments, the pass/fail test result generated by the test program is output to a printer, a display, or is stored in a memory. In other embodiments, the test program may be configured to test all pixels even if some pixels fail the comparison test. This may be of special interest in cases where only a few pixels had failed by a narrow margin. The percent differences in values for all pixels may be stored and statistics calculated to characterize the distribution of results within the test image. The output information may be expanded beyond a pass/fail criteria to a more detailed description of the pixels that failed or passed and the margin of failure individually or as a group. The output information may include one or more of the mean and variance of all absolute differences, a mean and variance of all acceptable absolute differences, a mean and variance of all unacceptable absolute differences, a maximum absolute difference, a minimum absolute difference and a range of absolute differences. This would give the user information on acceptable modifications of test parameter criteria that would enable the test image region to pass. In one embodiment, output information may include a histogram of differences, absolute differences, or % differences.

As used herein, the terms “array of pixels, array size, pixel array, and array” refers to one or more pixels, e.g., an array of pixels may include one pixel or may include a plurality of pixels. Where an array of pixels includes a single pixel, the average value of the array of pixels is the value of the single pixel.

As used herein, an average value of an array of pixels includes un-weighted averages or weighted averages. In some embodiments, the user may input a specific weighting function to be used to calculate weighting coefficients for each pixel position in the pixel array. Other weighting functions are possible and contemplated including functions with a radial dependence from a central pixel in an array, such as a conic function or a Gaussian function, and may include functions with both positively and negatively weighted regions.

As used herein, a “value” or a “color value” of a pixel may include any of various attribute values or other values of a pixel, including one or more of: color values (e.g., red,

green, and/or blue; or hue, saturation, and/or intensity), gray scale value, or other values that may be used to form an image.

Figure 4 – Adaptive Local Image Quantification Verification

Adaptive local image quantification verification is also a self-adaptive image comparison test program. In one embodiment, the user defines one or more regions (or portions) of the test image to be individually compared to a reference image and restricts the comparison to those pixels that are within the specified region or regions. A region of the test image may also be specified as the combination of two or more disjoint regions. This allows the test comparison to focus on one object, a small group of objects, a set of common objects, or a region with some common characteristic, such as a sky color. By repeating the comparison for several different regions of the test image, a set of Pass/Fail results can be independently determined for different objects or regions.

The value of a test image pixel $T(x,y)$ is first compared to the value of the corresponding reference image pixel $R(x,y)$. Corresponding pixels are pixels located at the same x and y coordinates in image space, one each from the test image and the reference image. If the difference between the values of the corresponding pixels is greater than a user specified limit, the average value of an array of reference image pixels centered on the pixel $R(x,y)$ is compared to the value of the test image pixel $T(x,y)$. If the value difference is still too large, the average value of an offset (shifted) reference image pixel array is compared to the value of the test image pixel. This effectively blurs the reference image to identify an acceptable match, and may allow an object (or objects) to have a small shift in position or size as compared to the same object in the reference image. In some embodiments the magnitude of an acceptable value difference and pixel offset may be specified by the user.

Figure 4 illustrates one set of embodiments of the adaptive local image quantification verification test program. The test program is first initialized 400 by storing the reference image and test image or by specifying where they may be accessed. Storing an image includes one or more steps of reading an image from a storage medium, receiving an image from the Internet or from an intranet, transferring a reference image from another computer system, or calculating a

value for each pixel of a reference image from equations describing each graphics operation used to create the test image. In one embodiment of the test program, a batch of images may be stored, with one or more test images and one or more reference images. The user may specify which test image and reference image comparisons to perform. A limit is specified for the maximum difference between the value of the test image pixel and the corresponding reference image pixel or pixel array. A limit is also specified for a maximum size reference image pixel array. The portion (region or regions) of the test image to be evaluated is specified and the first test image pixel to be compared is selected.

In some embodiments, the reference image array size may be controlled by an index parameter $k = 0, 1, 2, 3, \dots, N$ and initially may be set equal to zero. The selected array of reference image pixels is $(2k+1)$ by $(2k+1)$. This selects one of the set of pixel arrays $\{1 \times 1, 3 \times 3, 5 \times 5, 7 \times 7, \dots, \text{maximum array size}\}$. In other embodiments, the reference image array may be a rectangular array of pixels, a circular array of pixels, or a specified grouping of pixels. The reference image pixel array is selected so that it is centered on the pixel that corresponds to the position of the test image pixel. The average value of the reference image array is calculated and compared to the value of the test image pixel. If the absolute difference is greater than the specified limit, and the array size is less than the maximum array, then k is increased by one and the comparison is repeated for $k = k+1$. If the absolute difference is greater than the specified limit, and the array size is equal to the maximum array then an offset array test is performed to check for a shift in object position or size. If the offset array test also fails, the test is terminated and the comparison is labeled a failure. The offset array test is discussed in detail in the description of Figure 5. If the absolute difference is less than the specified limit, the test pixel passes and the test program checks for untested pixels. If there is an untested pixel, a comparison is initiated. The array index parameter is re-set to zero and the comparison process is repeated. If all pixels in the specified portion (or region) of the test image have successfully passed the comparison test, the comparison is labeled a pass.

In one embodiment, the pass/fail test result generated by the test program is output to a printer, a display, or is stored in a memory. In other embodiments, the test program may be

configured to test all pixels even if some pixels fail the comparison test. This may be of special interest in cases where only a few pixels had failed by a narrow margin. The percent differences in color values for all pixels may be stored and statistics calculated to characterize the distribution of results within the test image. The output information may be expanded beyond a pass/fail criteria to a more detailed description of the pixels that failed or passed and the margin of failure individually or as a group. The output information may include one or more of the mean and variance of all absolute differences, a mean and variance of all acceptable absolute differences, a mean and variance of all unacceptable absolute differences, a maximum absolute difference, a minimum absolute difference, a range of absolute differences, and a histogram of differences, absolute differences, or % differences. This would give the user information on acceptable modifications of test parameter criteria that would enable the test image region to pass.

Figure 5 – Offset Array Test

Figure 5 illustrates one embodiment of the offset array test for the adaptive local image quantification verification test program. The offset array test is first initialized 500 by selecting the pixel P in the maximum reference image array that has the minimum difference from the value of the test image pixel. This pixel P will become the new center pixel for a series of offset reference image pixel arrays. The series of arrays begins with array index parameter $k = 1$. The maximum difference and the maximum offset array size may be specified by the user or default to the values previously specified for the adaptive local image quantification verification test program.

The reference image offset array size is controlled by the index parameter $k = 1, 2, 3, \dots, N$. The selected array of reference image pixels is $(2k+1)$ by $(2k+1)$. This selects one of the set of pixel arrays $\{3 \times 3, 5 \times 5, 7 \times 7, \dots, \text{maximum array size}\}$. The offset reference image pixel array is selected so that it is centered on the pixel P that is offset from the pixel that corresponds to the position of the test image pixel 520. The average value of the offset reference image array is calculated 525 and compared to the value of the test image pixel 530. If the absolute difference is greater than the specified limit and the offset array size is less than the maximum

array 535, then k is increased by one 540 and the comparison is repeated for $k = k+1$ 515 through 530. If the absolute difference is greater than the specified limit and the offset array size is equal to the maximum offset array 535, then the test image pixel fails the offset array test 545. If the absolute difference is less than the specified limit, the test pixel passes the offset array test 550.

In other embodiments, the offset array test may not be centered on the pixel P, and the test may use a different algorithm such as searching for any reference image array that has an average value within a specified limit of the value of the test image pixel and is positioned within a specified distance from the reference image pixel that corresponds to the position of the test image pixel.

Figure 6 – Global Image Quantification Verification

Another set of embodiments of a test program involve blurring both the test image and the reference image. Global image quantification verification incorporates user-defined regions of interest with a specified error tolerance for each region. The user may specify certain regions as more important than others and focus a region on a particular object or group of objects. Global image quantification verification aims at a higher level image comparison by generating one measurement of error or image difference for an entire region of the test image. Each region of the test image and the reference image is divided into sub-regions and an average value is calculated for each test image sub-region and the corresponding sub-region in the reference image. The differences between the averages for corresponding sub-regions in the test and reference images are calculated. A test image region may be unacceptably different from a reference image if a normalized sum of the absolute differences exceeds a user specified maximum error.

Figure 6 illustrates one set of embodiments of a global image quantification verification test program. The test program is first initialized 600 by storing a reference image and test image or by specifying where they may be accessed. Storing an image includes one or more steps of reading an image from a storage medium, receiving an image from the Internet or an intranet, transferring a reference image from another computer system, or calculating a value for

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each pixel of a reference image from equations describing each graphics operation used to create the test image. In one embodiment of the test program, a batch of images may be stored, with one or more test images and one or more reference images. The user may specify which test image and reference image comparisons to perform. In one embodiment, the user specifies a region of the test image, a corresponding region of the reference image, the size of each of a plurality of sub-regions within the specified regions, and a maximum error. The user may specify a region by describing the individual pixels, a block of pixels, or multiple blocks of pixels that are contained in the region. The user may specify a sub-region size by choosing a pixel array or a block of pixels. In one embodiment, the sub-regions of a region are all the same size and form a grid across the extant of the region. In another embodiment, the user specifies multiple regions $T(i)$ of the test image, corresponding regions $R(i)$ of the reference image, and the size of each of a plurality of sub-regions within each $T(i)$ and $R(i)$. The one or more test image regions, when combined, may form a portion or all of the test image pixels. The user may also specify a maximum error(i) for each region $T(i)$.

The test program calculates the difference between the average of the values of all pixels in a sub-region of $T(i)$ and the average of the values of all pixels in a corresponding sub-region of $R(i)$ 610. The test program then calculates the sum of the absolute differences for all sub-regions in $T(i)$ and also calculates the sum of the average values for all sub-regions in $R(i)$ 615. A normalized error(i) for region $T(i)$ is calculated by dividing the sum of the absolute differences for all sub-regions in $T(i)$ by the sum of the average values for all sub-regions in $R(i)$ 620. The normalized error(i) for region $T(i)$ is then compared with the specified maximum error(i) 625. The test image region $T(i)$ passes if error(i) is less than the specified maximum error(i) 630, and fails if error(i) is more than the specified maximum error(i) 635. If multiple regions have been specified, the test program checks for untested regions 640, and initiates, if needed, a new error calculation for another region 645. When all specified regions have been tested, the test program generates test results for each tested region 650.

In some embodiments, the test result generated may be a simple pass or fail output to various devices including a display, a printer, or storage medium. In other embodiments generating a test result may include calculating and reporting statistics on the comparison that

may allow the user to better interpret why the test image failed or to alter the test criteria. Test results for a test image region, may include one or more of a mean and variance of all absolute differences between respective averages for corresponding sub-regions in the test image region and the reference image region, a mean and variance of all absolute differences less than a specified threshold, a mean and variance of all absolute differences greater than a specified threshold, a list of the sub-region differences that exceeded the specified maximum error, a maximum absolute difference, a minimum absolute difference, a range of absolute differences, and a histogram of the sub-region differences. In still other embodiments, the test program may store the differences calculated for each sub-region and the statistics for all sub-regions within a test image region.

Figure 7 – Regional Image Quantification Verification

Another set of embodiments of a test program involves blurring both the test image and the reference image and also allows for objects in the test image to be shifted in position or size relative to the same object in the reference image. Regional image quantification verification therefore aims at an image comparison that accepts minor pixel value differences and spatial shifts. One embodiment of the test program incorporates user-defined regions of interest with specified error tolerances for each region. This allows the user to specify certain regions as more important than others and to focus a region on a particular object or group of objects. Each region of the test image and reference image may be divided into sub-regions. The average value for each sub-region of the test image is compared to the average value of the corresponding reference image sub-region and also to nearby reference image sub-regions. A test image region may be unacceptably different from a reference image if for any one sub-region of the test image region, a reference image sub-region can not be found that has an average value difference and spatial shift less than user specified maximums.

Figure 7 illustrates one set of embodiments of a regional image quantification verification test program. The test program is first initialized 700 by storing a reference image and test image or by specifying where they may be accessed. Storing an image includes one or more steps of reading an image from a storage medium, receiving an image from the Internet or from

an intranet, transferring a reference image from another computer system, or calculating a value for each pixel of a reference image from equations describing each graphics operation used to create the test image. In one embodiment of the test program, a batch of images may be stored, with one or more test images and one or more reference images. The user may specify which test image and reference image comparisons to perform. In one embodiment, the user specifies a region of the test image, a corresponding region of the reference image, the size of each of a plurality of sub-regions within the specified regions, and a maximum difference. The user may specify a region by describing the individual pixels, a block of pixels, or multiple blocks of pixels that are contained in the region. The user may specify a sub-region size by choosing a pixel array or a block of pixels. In another embodiment, the user specifies multiple regions $T(i)$ of the test image, corresponding regions $R(i)$ of the reference image, and the size of each of a plurality of sub-regions within each $T(i)$ and $R(i)$. The user may also specify a maximum difference for each region $T(i)$. The one or more test image regions, when combined, may form a portion or all of the test image pixels.

The test program calculates the difference between the average of the values of all pixels in a sub-region of $T(i)$ and the average of the values of all pixels in a corresponding sub-region of $R(i)$ 710. The test program compares the absolute difference with the specified maximum difference 720. The test image sub-region passes if the absolute difference is less than the maximum difference and if sub-regions of $T(i)$ remain untested, a new sub-region is tested 730. If the absolute difference is greater than the maximum difference, the test program searches the reference image for a shifted sub-region that has an absolute spatial shift less than the specified maximum shift and an absolute difference less than the maximum difference 725. As used herein, a spatial shift is the distance in image space between the center of the shifted reference image sub-region and the center of the reference image sub-region that corresponds in x and y position in image space to the x and y position of the center of the test image sub-region. If a shifted sub-region of the reference image that meets these criteria is found, the test image sub-region passes, and if sub-regions of $T(i)$ remain untested, a new sub-region is then tested 730. In one embodiment, if a reference image sub-region that meets these criteria is not found the test image sub-region fails and consequently, the test image region $T(i)$ fails 735. In other embodiments, all test image sub-regions are evaluated and the differences and shifts are stored

for analysis and included in the test results for each region. If multiple regions have been specified, the test program checks for untested regions 740, and if necessary a new region T(i+1) is tested 745. When all regions have been tested, the test program generates test results for each tested region 750.

5 In some embodiments, the test result generated may be a simple pass or fail and may be output to various devices including a display, a printer, or storage medium. In other embodiments, generating a test result may include calculating and reporting statistics on the comparison that may allow the user to better interpret why the test image failed or to alter the test criteria. Test results for a test image region, may include one or more of a mean and variance of
10 all absolute differences between respective averages for corresponding sub-regions in the test image region and the reference image region, a mean and variance of all absolute differences less than a specified difference, a mean and variance of all absolute differences greater than a specified difference, a list of the sub-regions with differences that exceeded the specified maximum difference, a maximum absolute difference and shift, a minimum absolute difference and shift, a range of absolute differences and shifts, a histogram of differences, and a histogram of shifts. In still other embodiments, the test program may store the differences and shifts determined for each sub-region and the statistics for all sub-regions within a test image region.

Although the embodiments above have been described in considerable detail, other embodiments are possible and contemplated. Numerous variations and modifications will become apparent to those skilled in the art once the above disclosure is fully appreciated. It is intended that the following claims be interpreted to embrace all such variations and modifications. Note the headings used herein are for organizational purposes only and are not meant to limit the description provided herein or the claims attached hereto.